

INTRODUCTION TO DYNAMICAL SYSTEMS

Solutions Problem Set 7

Exercise 1. By considering the map $T: S^1 \rightarrow S^1$ given by $T(z) = z^{10}$, show that for almost every $x \in (0, 1]$ it holds that, writing

$$x = 0.x_1x_2\dots$$

in decimal expansion, we have that

$$\lim_{N \rightarrow \infty} \frac{1}{N} |\{j \in [1, 2, \dots, N]: x_j = 0\}| = \frac{1}{10}.$$

Solution. We can apply the ergodic theorem to the function $\mathbb{1}_{(0,1)}$ and consider the map T acting on $(0, 10]$ periodically (which we relabel $\tilde{T}$) to find

$$\lim_{N \rightarrow \infty} \frac{1}{N} |\{j \in [1, 2, \dots, N]: x_j = 0\}| = \frac{1}{10} \int_{(0,10]} \mathbb{1}_{(0,1)}(t) dt = \frac{1}{10}, \quad \text{a.e. } x \in (0, 1].$$

□

Exercise 2. Complete the proof of Lemma 1.2 in Lecture8.pdf, i.e. determine the constants $c, \theta_{\pm}$.

Solution. Recalling the notation from the proof, we have subspaces $\mathbb{R}^n = E_+ \oplus E_-$, such that by setting $A_{\pm} = A|_{E_{\pm}}$ to a hyperbolic matrix A , we can associate $\theta_{\pm} \in (0, 1)$ and a constant $c \geq 0$ such that

$$|A_+^n(x)| \leq c\theta_+^n |x|, \quad x \in E_+, \quad |A_-^n(x)| \leq c\theta_-^n |x|, \quad x \in E_-, \quad n \geq 0.$$

To give $\theta_{\pm}$ and c explicitly, we recall the *spectral radius* r_B of a matrix B together with the formula,

$$r_B := \max \{|\lambda| : \lambda \in \sigma(B)\}, \quad \lim_{n \rightarrow \infty} \|B^n\|^{1/n} = r_B,$$

where $\sigma(B)$ is the spectrum of B and $\|\cdot\|$ is the operator norm. Given that the eigenvalues of A_+ all belong to $(0, 1)$, we must have $r_{A_+} < 1$, and therefore for some $N \geq 0$, we have the estimates

$$\|A_+^n\|^{1/n} \leq \theta_+ < 1, \quad \forall n \geq N,$$

where θ_+ can be taken arbitrarily close to r_{A_+} depending only on N . Now, choosing

$$c = \max \left\{ \frac{\|A_+^n\|}{\theta_+^n} : n \in \{1, \dots, N\} \right\},$$

we find that

$$\|A_+^n\|^{1/n} \leq c\theta_+, \quad \forall n < N$$

holds true, and we conclude that these are indeed the parameters in Lemma 1.2 thanks to the definition of the operator norm $\|\cdot\|$. The estimates for $|A_-^n x|$ follow by applying the same argument to the linear map A_-^{-1} . □

Exercise 3. Let $A \in \text{Mat}(n \times n; \mathbb{R})$ be a hyperbolic matrix, and let

$$\phi(x) = Ax + \hat{\phi}(x), \quad \psi(x) = Ax,$$

where $\hat{\phi}$ is in $C_b^1(\mathbb{R}^n, \mathbb{R}^n)$, i.e., bounded and continuously differentiable. Further assume that the Lipschitz constant for $\hat{\phi}$ is sufficiently small so that the conditions of Proposition 4.2 of Lecture8.pdf are satisfied. Then show that if $\phi(0) = 0$ and¹

$$\text{trace} \left(D\hat{\phi}(0) \right) \neq 0,$$

the homeomorphism h whose existence is asserted in Proposition 4.2 cannot be a C^1 diffeomorphism.

Solution. Since h solves $\phi \circ h = h \circ \psi$, we have

$$A \cdot h + \hat{\phi} \circ h = h \circ A,$$

and by computing the Jacobian we reach

$$A \cdot Dh_x + D\hat{\phi}_{h(x)} \cdot Dh_x = Dh_x \cdot A$$

We then evaluate at $x = 0 = h(0)$ to get, assuming that h is a diffeomorphism, that

$$-A + Dh_0 \cdot A \cdot (Dh_0)^{-1} = D\hat{\phi}_0$$

But then we necessarily have

$$\text{trace} \left(D\hat{\phi}_0 \right) = 0,$$

which contradicts the hypotheses. □

¹Here $D\hat{\phi}$ is the Jacobian of the map